

Advances in the Formalisation of Univariate Taylor Models in COQ

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Outline

- 1 Introduction
- 2 Taylor Models for Basic Functions
- 3 Taylor Models for Composite Functions
- 4 Benchmarks
- 5 Conclusion

Context and Motivations

- What?** Compute polynomial approximations of univariate functions with certified error bounds: $\forall x \in \mathbf{I}, |f(x) - P(x)| \leq \epsilon$
- Why?** The correctness of such bounds is a key part of the reliability of numerical software implementing mathematical functions
- How?** Rely on Taylor Models, and interval arithmetic (cf. next slide)

Overview of Interval Arithmetic (IA)

- Interval = pair of real numbers (or floating-point numbers)
- E.g., $[3.1415, 3.1416] \ni \pi$
- Operations on intervals, e.g., $[2, 4] - [0, 1] := [2 - 1, 4 - 0] = [1, 4]$, with the enclosure property: $\forall x \in [2, 4], \forall y \in [0, 1], x - y \in [1, 4]$.
- Tool for bounding the range of functions
- **Dependency problem:** for $f(x) = x \cdot (1 - x)$ and $\mathbf{X} = [0, 1]$, a naive use of IA gives $\text{eval}(f, \mathbf{X}) = [0, 1]$ while the image of \mathbf{X} by f is $[0, \frac{1}{4}]$
- IA is not directly applicable to bound approximation errors $e := f - P$ which notably raise some **cancellation** issues

Overview of Taylor Models (TMs)

The function f is replaced with (P, Δ) , where $P = \sum_{i=0}^n P_i \cdot (x - x_0)^i$ and Δ is an interval.

A Taylor Model (P, Δ) over I approximates a whole set of functions:

$$\llbracket (P, \Delta) \rrbracket_I = \{f : I \rightarrow \mathbb{R} \mid \forall x \in I, f(x) - P(x) \in \Delta\}.$$

Taylor-Lagrange remainder and validity predicate

Theorem (Taylor-Lagrange)

If f is $n + 1$ times derivable on I , then $\forall x \in I, \exists \xi$ between x_0 and x s.t.:

$$f(x) = \underbrace{\left(\sum_{i=0}^n \frac{f^{(i)}(x_0)}{i!} (x - x_0)^i \right)}_{\text{Taylor expansion}} + \underbrace{\frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)^{n+1}}_{\Delta_n(x_0, x, \xi)}.$$

Definition (`i_validTM`)

(P, Δ) is a valid Taylor Model for f over I around \mathbf{x}_0 if $\mathbf{x}_0 \subset I$, $0 \in \Delta$, and

$$\forall \mathbf{x}_0 \in \mathbf{x}_0, \exists \alpha_0 \in P_0, \dots, \alpha_n \in P_n, \forall x \in I, f(x) - \sum_{i=0}^n \alpha_i (x - x_0)^i \in \Delta.$$

Methodology of Taylor Models

Define arithmetic operations on Taylor Models:

- TM_{add} , TM_{mul} , TM_{comp} , and TM_{div}
- E.g., $\text{TM}_{\text{add}} : \left((P_1, \Delta_1), (P_2, \Delta_2) \right) \mapsto (P_1 + P_2, \Delta_1 + \Delta_2)$.

A two-step strategy:

- Apply these operations recursively on the structure of the function
- Use Taylor-Lagrange remainder for atoms (basic functions)

Why using this 2-step strategy for composite functions?

Interval enclosures Δ for $\Delta_n(x_0, x, \xi)$ can be **largely overestimated**.

Example

$f(x) = e^{1/\cos x}$ over $I = [0, 1]$ around $x_0 = \frac{1}{2}$, with $n = 13$.

- Automatic differentiation and Taylor-Lagrange formula:
 $\Delta = [-1.94 \cdot 10^2, 1.35 \cdot 10^3]$

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- Automatic differentiation and Taylor-Lagrange formula:
 $\Delta = [-1.94 \cdot 10^2, 1.35 \cdot 10^3]$
- Taylor Models:
 $\Delta = [-8.74 \cdot 10^{-4}, 4.63 \cdot 10^{-3}]$

The COQ formal proof assistant

We use COQ for

- programming
 - richly typed functional language
 - specify algorithms and theorems
- proving
 - use higher-order logic
 - build proofs interactively
 - develop automatic tactics
 - check proofs



The COQ formal proof assistant

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- programming
 - richly typed functional language
 - specify algorithms and theorems
 - **perform computations**
- proving
 - use higher-order logic
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COQ libraries involved in the formalisation

- SSReflect
 - libraries on arithmetic, lists, and “big” operators
 - tactic facilities
- CoqInterval
 - Abstract interface for intervals
 - Instantiation to intervals with floating-point bounds
 - Formal verification with respect to the Reals library

for $x, y : \mathbb{R}$

and $\mathbf{X}, \mathbf{Y} : \mathbb{IR}$

$$x \in \mathbf{X} \wedge y \in \mathbf{Y} \implies x + y \in \mathbf{X} + \mathbf{Y}$$

$$x \in \mathbf{X} \implies \exp(x) \in \mathbf{exp}(\mathbf{X})$$

Generic computation of sharp remainders for basic functions

Algorithm (Zumkeller's technique)

Input: F : interval evaluator for function f ; $\mathbf{x}_0 \subset I$ and $n \in \mathbb{N}$

Input: $T(\mathbf{y}_0, n)$: order- n Taylor polynomial of f around \mathbf{y}_0

Output: (P, Δ)

- 1: $P \leftarrow T(\mathbf{x}_0, n)$
- 2: $\Gamma \leftarrow [X^{n+1}] T(I, n + 1)$
- 3: **if** $(\sup \Gamma \leq 0$ **or** $\inf \Gamma \geq 0)$ **and** I is bounded **then**
- 4: $a \leftarrow [\inf I, \inf I]$
- 5: $b \leftarrow [\sup I, \sup I]$
- 6: $\Delta_a \leftarrow F(a) - P(a - \mathbf{x}_0)$
- 7: $\Delta_b \leftarrow F(b) - P(b - \mathbf{x}_0)$
- 8: $\Delta_{x_0} \leftarrow F(\mathbf{x}_0) - P(\mathbf{x}_0 - \mathbf{x}_0)$
- 9: $\Delta \leftarrow \Delta_a \vee \Delta_b \vee \Delta_{x_0}$
- 10: **else**
- 11: $\Delta \leftarrow \Gamma \times (I - \mathbf{x}_0)^{n+1}$
- 12: **end if**

A generic formalization

When formalizing Taylor Models (P, Δ) , focus on being generic w.r.t.

- the type of coefficients of polynomial P ,
- the type of P and the implementation of related operations
- the type of interval Δ
- the correctness proofs, relying on COQ's standard library Reals

D -finite functions (a.k.a. holonomic functions)

Definition

A D -finite function is a solution of a homogeneous linear ordinary differential equation with polynomial coefficients:

$$a_r(x)y^{(r)}(x) + \cdots + a_1(x)y'(x) + a_0(x)y(x) = 0, \text{ for given } a_k \in \mathbb{K}[X].$$

Property

The Taylor coefficients of these functions satisfy a *linear recurrence with polynomial coefficients*

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Property

The Taylor coefficients of these functions satisfy a *linear recurrence with polynomial coefficients* → **fast numerical computation of the coefficients**

Example (the exponential function)

The Taylor coefficients of \exp at x_0 satisfy the recurrence

$$\forall n \in \mathbb{N}, (n+1)u_{n+1} = u_n, \text{ with } u_0 = \exp(x_0) \text{ as an initial condition.}$$

\ln , \sin , \arcsin , \sinh , $\operatorname{arcsinh}$, \arctan , $\operatorname{arctanh}$... are D -finite; \tan is not

Proofs for composite functions

Proof of the algorithm for each algebraic rule

- TM_{add} : straightforward
- TM_{mul} : rely on truncated multiplication of polynomials
- TM_{comp} : rely on TM_{mul} , TM_{add} and TMs for constant functions
- TM_{div} : it's a TM for $f \times \left(\left(x \mapsto \frac{1}{x} \right) \circ g \right)$

Comparison with a dedicated tool implemented in C

Sollya [S.Chevillard, M.Joldeş, C.Lauter]

- written in C
- based on libraries MPFR, MPFI
- contains an implementation of univariate Taylor Models
- in an imperative-programming framework
- polynomials as arrays of coefficients

CoqApprox

- formalized in COQ
- based on the CoqInterval library
- implements Taylor Models using a similar algorithm
- in a functional-programming framework
- polynomials as lists of coefficients (linear access time)

Validity predicate for floating-point Taylor Models

From any pair (P, Δ) that satisfies `i_validTM`, we can easily produce a pair (P, Δ') where P is polynomial with floating-point coefficients s.t.:

Definition (`f_validTM`)

(P, Δ') is a valid TM for f over I around x_0 if we have $x_0 \subset I$, $0 \in \Delta'$, and

$$\forall \xi_0 \in x_0, \quad \forall x \in I, \quad f(x) - \sum_i P_i \cdot (x - \xi_0)^i \in \Delta'.$$

In the code, the function `i2f_tm` transforms (P, Δ) into (P, Δ') .

Some benchmarks for basic functions

	Execution time			Approximation error		
	COQ	Sollya	ratio	naive COQ	COQ	Sollya
$f(x) = \sin x$ $I = [-1, 1]$ order=80 prec=500	0.146s	0.092s	1.6	$1.79 \cdot 2^{-402}$	$1.79 \cdot 2^{-402}$	$1.79 \cdot 2^{-402}$
$f(x) = \frac{1}{x}$ $I = [1, 3]$ order=100 prec=125	0.022s	0.165s	0.13	$1 \cdot 2^0$	$1 \cdot 2^{-101}$	$1 \cdot 2^{-101}$
$f(x) = \sqrt{x}$ $I = [1, 3]$ order=100 prec=125	0.037s	0.169s	0.22	$1.98 \cdot 2^{-12}$	$1.60 \cdot 2^{-112}$	$1.60 \cdot 2^{-112}$
$f(x) = \frac{1}{\sqrt{x}}$ (as a basic function) $I = [1, 3]$ order=100 prec=125	0.029s	0.424s	0.068	$1.80 \cdot 2^{-5}$	$1.27 \cdot 2^{-105}$	$1.27 \cdot 2^{-105}$

Some benchmarks for composite functions

	Execution time			Approximation error		
	COQ	Sollya	ratio	naive COQ	COQ	Sollya
$f(x) = e^x \sin x$ $I = [-\frac{3}{2}, \frac{3}{2}]$ order=100 prec=500	1.010s	0.306s	3.3	$1.63 \cdot 2^{-423}$	$1.63 \cdot 2^{-423}$	$1.63 \cdot 2^{-423}$
$f(x) = e^{1/\cos x}$ $I = [0, 1]$ order=100 prec=100	52.92s	0.653	81	$1.97 \cdot 2^{-49}$	$1.99 \cdot 2^{-89}$	$1.98 \cdot 2^{-89}$
$f(x) = \frac{\sin x}{\cos x}$ $I = [-1, 1]$ order=100 prec=100	11.15s	0.570s	20	$1.45 \cdot 2^{26}$	$1.12 \cdot 2^{-64}$	$1.82 \cdot 2^{-96}$
$f(x) = \frac{1}{\sqrt{x}}$ (as a composite function) $I = [1, 3]$ order=100 prec=125	37.683s	0.424s	89	$1.98 \cdot 2^{-12}$	$1.27 \cdot 2^{-105}$	$1.27 \cdot 2^{-105}$

Brief conclusion

CoqApprox: a modular formalization of rigorous polynomial approximation using Taylor Models in the COQ proof assistant

- with a generic approach involving D -finite functions
 - taking advantage of the CoqInterval library for interval arithmetic
- ability to efficiently compute some formally verified TMs in COQ

Proof status

Fun/Op	Reals	CoqInterval	CoqApprox
cst	☒	☒	☒
id	☒	☒	☒
inv	☒	☒	☒
$\sqrt{\cdot}$	☒	☒	☒
$\frac{1}{\sqrt{\cdot}}$	☒	☒	☒
exp	☒	☒	☒
sin	☒	☒	☒
cos	☒	☒	☒
arctan	☒	☒	☐
ln	☒	☐	☐
arcsin	☐	☐	☐
arccos	☐	☐	☐
TM _{add}			☒
TM _{mul}			☒
TM _{comp}			☒
TM _{div}			☒

Functions missing from support libraries

Functions missing from the Reals library

- cannot provide a proof for the Taylor Model
- adding them is so far done in a case-by-case manner
- find a generic way of adding a new function to Reals
- e.g. by using a differential equation or a recurrence relation as definition
- **need to provide the n -th derivatives of the function**

Functions missing from CoqInterval

- cannot provide an initial value for the Taylor Model
- just implement the missing functions in CoqInterval
- may use some extra techniques, such as fixed point theorems

Perspectives for CoqApprox

- Add more functions (\cosh , \tan , etc.) and prove them
- Optimize the multiplication algorithm for Taylor Models
- Implement Chebyshev Models \leadsto tighter remainders
- Taylor Models with Relative Remainder?
- Combine TMs with some polynomial global optimization technique
 - E.g., Bernstein polynomials
- Consider the possible generalization to the multivariate case
- Investigate ways to ease the definition of RPAs from the ODE
- Investigate the possible use of an “affine arithmetic” module
- Investigate RPAs based on other families of orthogonal polynomials
- Consider alternative techniques for verifying error bounds
 - fixed-point theorems?
 - majorant series?

End of the Talk

Thank you for your attention!

The TaMaDi project homepage:

<http://tamadi.gforge.inria.fr/>

